Diffusion model in Image Transforms Inversion tasks

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Solving modern machine learning tasks requires development of new methods of solving corresponding inverse problems. Majority of real-world inverse problems are ill-posed and therefore require regularization. For some digital signal processing tasks, such as image de-noising, image restoration, superresolution, image improvement, the choice of regularization technique is nontrivial, whereas significantly influences the corresponding solution.

In our work we study diffusion model for inversion of image transforms. For inverse problem

$$Ax = y \tag{1}$$

we consider Bayesian approach, or maximum a posteriori probability (MAP) estimate, which finds such an x, that maximises the conditional probability p(x|y). According to Bayes rule

$$p(x|y) = \frac{p(x,y)}{p(y)} = \frac{p(y|x)p(x)}{\int p(y|x)p(x)dx} \propto p(y|x)p(x),$$

therefore maximisation of p(x|y) corresponds to the following problem:

 $\underset{x}{\arg\min}(-\log p(y|x) - \log p(x)).$

Obviously, real probability distribution functions are unknown. Therefore instead of it we solve the following heuristics

$$\hat{x} = \arg\min_{x} \{ l(x, y) + \alpha \rho(x) \}, \tag{2}$$

where l(x, y) is a loss function and $\rho(x)$ is a regularization term.

Let's slightly modify (2):

$$\hat{x} = \underset{x,v}{\operatorname{arg\,min}} \{ l(x,y) + \alpha \rho(v) \}, x = v.$$

It allows us to apply Alternating Direction Method of Multipliers (ADMM) from the paper [2], using Lagrangian:

$$L_{\lambda}(x, v, u) = l(x, y) + \alpha \rho(v) + \frac{\lambda}{2} ||x - v + u||^2 - \frac{\lambda}{2} ||u||^2$$

It leads to iterative solving following minimization tasks till convergence:

$$\hat{x} \longleftarrow \underset{x}{\operatorname{arg\,min}} L(x, \hat{v}, u)$$
$$\hat{v} \longleftarrow \underset{x}{\operatorname{arg\,min}} L(\hat{x}, v, u)$$
$$u \longleftarrow u + (\hat{x} - \hat{v})$$

or in terms of (2)

$$\hat{x} = \min_{x} l(x, y) + \beta \|x - v\|^2,$$
$$\hat{v} = \min_{v} \alpha \rho(v) + \beta \|x - v\|^2.$$

In such a way, instead of one inverse problem with regularization scheme we've got two interconnected minimization problems, iterative solving of which allows us to find solution for the initial problem. Having some initial x_0 and v_0 we iterate

$$x_{i+1} = \min_{x} l(x, y) + \beta ||x - v_i||^2,$$

$$v_{i+1} = \min_{y} \alpha \rho(v) + \beta ||x_i - v||^2.$$

Let's consider some operator $D: X \mapsto X$, that preserves x as a solution, i.e.

$$AD(x,\sigma) = y,$$

for example, for super-resolution task instead of D a denoising operator may be used.

For diffusion model regularization term $\rho(x)$ is $\alpha\rho(x) = \alpha x^T [x - D(x, \sigma)]$. Under mild conditions (differentiability, local homogeneity, and symmetric Jacobian for D) we may apply gradient descent:

$$x_{k+1} = x_k - \mu [A^T (Ax_k - y) - \alpha [x_k - D(x_k, \sigma)]].$$

In our work we study convergence rates of the proposed diffusion model and approximation error, illustrating it with numerical experiments.

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